

TOPICS : KINEMATICS SOLUTION

1. $v_x = \frac{dx}{dt} = \frac{d}{dt}(at) = a$
 $v_y = \frac{dy}{dt} = \frac{d}{dt}(bt^2 + ct) = 2bt + c$
 At $t = 1s, v_y = 2b + c$
 The magnitude of velocity at $t = 1s$ is given by
 $v = \sqrt{v_x^2 + v_y^2} = \sqrt{a^2 + (2b + c)^2}$

2. As earth's rotation and revolution are in the same direction, relative to sun

$$v_{\text{day}} = v_0 - v_S = v_0 - R\omega$$

and $v_{\text{night}} = v_0 + v_S = v_0 + R\omega$

So $v_{\text{night}} > v_{\text{day}}$, i.e., objects on earth move faster in night than in day. However, $v_{\text{night}} > v_{\text{day}} = 2R\omega \approx 1 \text{ km/s}$ which is much lesser than $v_0 = 30 \text{ km/s}$

3. (a) $t_A = \sqrt{\frac{2h}{g}}$ while $t_B = \frac{(u^2 + 2gh)^{1/2} - u}{g}$

(b) $v_A = \sqrt{2gh}$ while $v_B = \sqrt{u^2 + 2gh}$

4.

5. $R_P = R_Q \Rightarrow \frac{(\sqrt{2}u)^2 \sin(2 \times 15^\circ)}{g} = \frac{u^2 \sin 2\theta}{g}$

$$1 = \sin 2\theta$$

$$\theta = 45^\circ$$

6. The co-ordinates of a point on one trajectory relative to other will be

$$x = x_2 - x_1 = (u_2 \cos \theta_2 - u_1 \cos \theta_1) t$$

and

$$y = \left(u_2 \sin \theta_2 t - \frac{1}{2} g t^2 \right) - \left(u_1 \sin \theta_1 t - \frac{1}{2} g t^2 \right)$$

$$= (u_2 \sin \theta_2 - u_1 \sin \theta_1) t$$

So, $\frac{y}{x} = \left(\frac{u_2 \sin \theta_2 - u_1 \sin \theta_1}{u_2 \cos \theta_2 - u_1 \cos \theta_1} \right) = \text{constt.} = m$

or $y = mx$ which is a straight line

7. $H = \frac{u^2 \sin^2 \theta}{2g}$ and $R = \frac{u^2 \sin 2\theta}{g}$

$$\frac{H}{R} = \frac{\sin^2 \theta}{2 \sin 2\theta} = \frac{\sin^2 \theta}{4 \sin \theta \cos \theta} = \frac{1}{4} \tan \theta$$

8. $t_1 = \frac{2u \sin \theta}{g}$ and $t_2 = \frac{2u \sin(90^\circ - \theta)}{g} = \frac{2u \cos \theta}{g}$

$$\therefore t_1 t_2 = \frac{2u \sin \theta}{g} \times \frac{2u \cos \theta}{g} = \frac{2}{g} \left(\frac{u^2 \sin 2\theta}{g} \right) = \frac{2R}{g}$$

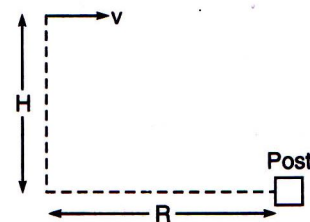
9. Time taken by a body to go up and come down a height h is given by $t = 2\sqrt{(2h/g)} = \sqrt{(8h/g)}$. So, if y is the height of highest point above higher level, time taken to go up and

come down $\Delta T_H = \sqrt{(8y/g)}$ while for lower level $\Delta T_L = \sqrt{[8(y+h)/g]}$.

$$\therefore \Delta T_L^2 - \Delta T_H^2 = \frac{8(y+H)}{g} - \frac{8y}{g} = \frac{8H}{g}$$

or $g = \frac{8H}{(\Delta T_L^2 - \Delta T_H^2)}$

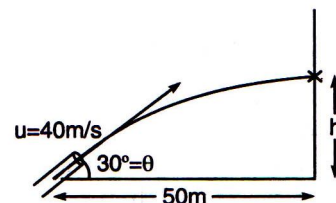
10.



$$H = \frac{1}{2} g t^2$$

$$R = v \times T$$

11.



$$h = x \tan \theta - \frac{g x^2}{2u^2 \cos^2 \theta}$$

12.

$$R_{\text{max}} = \frac{u^2}{g}$$

$$H_{\text{max}} = \frac{u^2}{2g}$$

13.

14. Let the initial position vector is $x'\hat{i} + y'\hat{j} + z'\hat{k} = \vec{r}_A$.

Now, $a_x = \frac{12}{3}, a_y = -\frac{3}{3}, a_z = \frac{21-10}{3}$

$\vec{r}_B = 15\hat{i} + 7\hat{j} - 6\hat{k}$

Now, $15 - x' = u_{x'} \times 2 + \frac{1}{2} \times 4 \times (2)^2$

$7 - y' = u_{y'} \times 2 + \frac{1}{2} (-1) \times (2)^2$

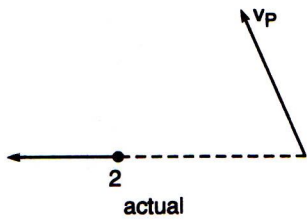
$-6 - z' = u_{z'} \times 2 + \frac{1}{2} \times \frac{11}{3} \times (2)^2$

$\vec{v}_B = 12\hat{i} + \hat{j} - 4\hat{k}$

$\vec{v}_B = v_x \hat{i} + v_y \hat{j} + v_z \hat{k}$

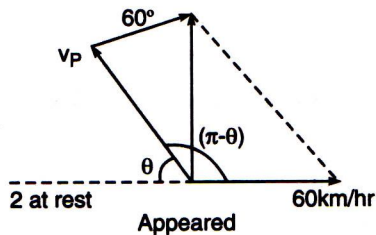
$\frac{v_x - u_{x'}}{a_x} = t, \frac{v_y - u_{y'}}{a_y} = t, \frac{v_z - u_{z'}}{a_z} = t$

14. For observer 2.



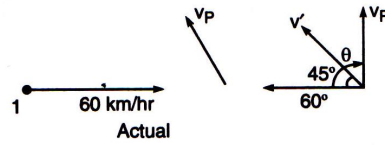
$v'^2 = v_p^2 + (60)^2$

$\tan 90^\circ = \frac{v_p \sin(\pi - \theta)}{60 + v_p \cos(\pi - \theta)}$



$v_p \cos \theta = 60^\circ$... (ii)

For observer 1.



$\tan 45^\circ = \frac{v_p \sin \theta}{60 + v_p \cos \theta}$

$60 + v_p \cos \theta = v_p \sin \theta$

$v_p \sin \theta = 120^\circ$... (iii)

$\tan \theta = 2$

15. Position vector of ship after 't' hours from 12 noon is,

$\vec{r}_s = \vec{r}_{os} + \vec{v}_s t = (3\hat{i} - \hat{j}) + (3\hat{i} + 4\hat{j})t$... (i)

Position vector of motor boat at that instant

$\vec{r}_B = (-6\hat{i} - 2\hat{j}) + (a\hat{i} + b\hat{j})(1+t)$... (ii)

where $a\hat{i} + b\hat{j} = \vec{v}_B$ (velocity of motor boat)

Given $a^2 + b^2 = 53$... (iii)

when they intercept, $\vec{r}_s = \vec{r}_B$

Equate coefficients of \hat{i} and \hat{j} and use equation (iii)

we get $b = 2$ and $\frac{34}{5}$; with $b = \frac{34}{5}$ time 't' comes out to be

negative which is not possible so $b = 2$,

from this $a = 7$ and $t = \frac{1}{2}$.

Position vector of point of interception is $\frac{a}{2}\hat{i} + \hat{j}$.

16.

$|\vec{V}_{M/R}| = 4.0 \text{ km/hr,}$

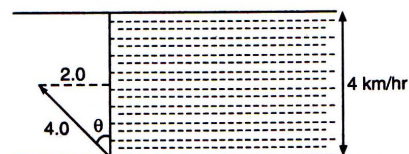
$|\vec{V}_{R/G}| = 2.0 \text{ km/hr}$

$\sin \theta = \frac{2}{4} = \frac{1}{2}$

$\theta = 30^\circ$

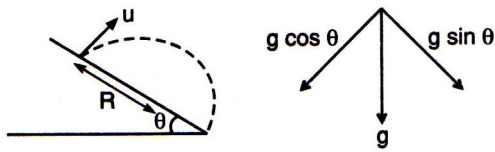
$t = \frac{4.0}{4 \cos 30^\circ} = \frac{2}{\sqrt{3}} \text{ hr}$

$d_{\text{drift}} = V_R \times t$



In order to cross the river in minimum time he should go perpendicular to river flow.

17.



$$R = \frac{1}{2} g \sin \theta (T)^2$$

$$T = \frac{2u}{g \cos \theta}$$

18.

$$T = \frac{2u}{g} = \frac{2 \times 20}{10} = 4 \text{ sec}$$

Distance travelled by the cannon.

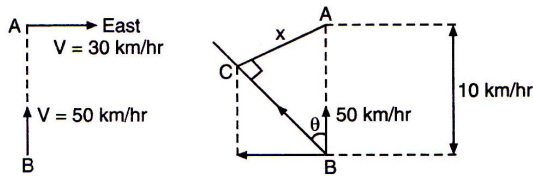
$$s = 30 \times 4 \times \frac{5}{18} \text{ m}$$

$$s = 120 \times \frac{5}{18}$$

$$s = \frac{100}{3} \text{ m}$$

19.

$$\frac{x}{10} = \sin \theta$$



$$x = 10 \sin \theta \quad \text{Closest approach}$$

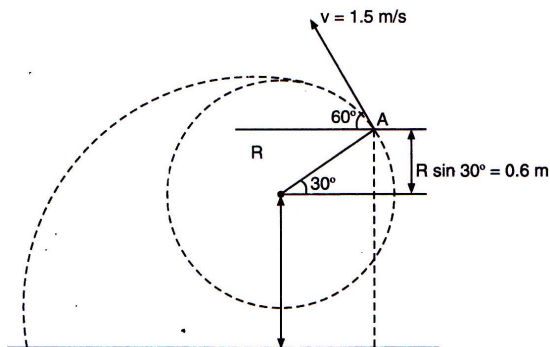
$$t = \frac{BC}{\sqrt{(30)^2 + (50)^2}}$$

20.

(a) $h = 1.5 + 0.6 = v \sin 60^\circ t - \frac{1}{2} g t^2$

$R_1 = v \cos 60^\circ t$

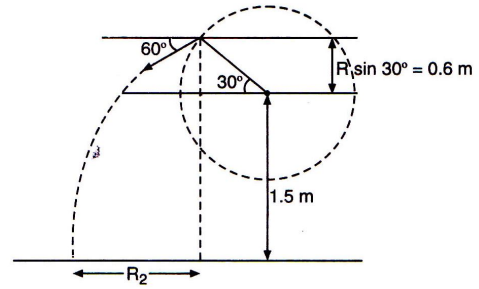
Solving $R_1 = 600 \text{ m}$



(b) $h = 1.5 + 0.6 = -v \sin 60^\circ t - \frac{1}{2} g t^2$

$R_1 = v \cos 60^\circ t$

Solving $R_2 = 0.402 \text{ m}$



(c) $a = \frac{v^2}{R} = \frac{(1.5)^2}{1.2} = 1.87 \text{ m/s}^2$ towards centre

(d) $a = g = 9.8 \text{ m/s}^2$ down

21.

Velocity of 1st particle at any instant 't'

$$\vec{v}_1 = u_1 \cos \theta_1 \hat{i} + (u_1 \sin \theta_1 - g t) \hat{j} \quad \dots(i)$$

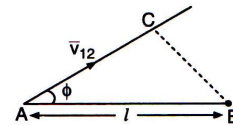
Velocity of 2nd particle at the same instant 't'

$$\vec{v}_2 = u_2 \cos \theta_2 (-\hat{i}) + (u_2 \sin \theta_2 - g t) \hat{j} \quad \dots(ii)$$

∴ Velocity of 1st particle w.r.t. 2nd particle

$$\vec{v}_{12} = \vec{v}_1 - \vec{v}_2 = (u_1 \cos \theta_1 + u_2 \cos \theta_2) \hat{i} + (u_1 \sin \theta_1 - u_2 \sin \theta_2) \hat{j} \quad \dots(iii)$$

$$\tan \phi = \frac{u_1 \sin \theta_1 - u_2 \sin \theta_2}{u_1 \cos \theta_1 + u_2 \cos \theta_2} \quad \dots(iv)$$



(a) Separation when they are closest is $BC = l \sin \phi$

(b) $t = \frac{AC}{|\vec{v}_{12}|} = \frac{l \cos \phi}{|\vec{v}_{12}|}$

$$|\vec{v}_{12}| = \sqrt{(u_1 \cos \theta_1 + u_2 \cos \theta_2)^2 + (u_1 \sin \theta_1 - u_2 \sin \theta_2)^2}$$

(c) If they collide then BC (minimum separation) = 0

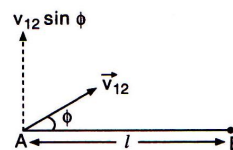
i.e., $\phi = 0$

∴ $\tan \phi = 0$

⇒ $u_1 \sin \theta_1 = u_2 \sin \theta_2$ from equation (iv)

(d) Velocity of approach

$$= u_1 \cos \theta_1 + u_2 \cos \theta_2$$



(e) $\omega_{12} = \omega_{AB} = \frac{v_{12} \sin \phi}{l}$

$$\omega_{12} = \frac{u_1 \sin \theta_1 - u_2 \sin \theta_2}{l}$$